A new approach to the analysis of vessels RTD curves

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Abstract

Mathematical models for the evaluation of residence time distribution (RTD) curves on a large variety of vessels are presented. These models have been constructed by combination of di¤erent tanks or volumes. In order to obtain a good representation of RTD curves, a new volume (called convection di¤usion volume) is introduced. The convection-di¤usion volume allows the approximation of di¤erent experimental or numerical RTD curves with very simple models. An algorithm has been developed to calculate the parameters of the models for any given set of RTD curve experimental points. Validation of the models are carried out by comparison with experimental RTD curves taken from literature and with a numerical RTD curve obtained by three dimensional simulation of the ‡ow inside a tundish.

I Introduction

The residence time of an element of ‡uid is the time it spends inside the vessel. Since di¤erent elements of ‡uid spend di¤erent times inside the vessel, there is a distribution of residence times for each vessel. The residence time distribution (RTD) gives important information about the behavior of the ‡ow inside the di¤erent vessels of the continuous caster. Both experimental and numerical techniques can be employed

to obtain the RTD [1]. In both cases the basic idea is to inject a pulse of a tracer at the entrance of the vessel and analyze the concentration of tracer at the exit as function of time. This function is known as the RTD curve. RTD curves are generally represented in terms of dimensionless variables (to be de...ned in the following section) and typically take the shape of the curve depicted in Figure 1.



Fig. 1: Typical RTD curve.

Experimental RTD curves are obtained in water models by the injection of a salt solution or a dye as a tracer. In the former case the concentration at the exit of the vessel is obtained by measuring the conductivity of the ‡uid. In the latter, colorimetry or spectrophotometry techniques are used to get the concentration.

RTD curves can also be obtained by numerical methods. In this case the ...rst step is to calculate the turbulent ‡ow inside the vessel. Di¤erent techniques could be applied to solve the steady state turbulent Navier-Stokes equations. The k-" method, where k is the turbulent kinetic energy and " is the turbulent kinetic energy dissipation rate, is the most popular [2]. Once the velocity distribution inside the vessel is obtained, the addition of tracer needs to be numerically simulated. A turbulent convection di¤usion equation for the concentration of tracer must be solved. A narrow step function has to be imposed at the entrance as boundary condition to simulate the tracer pulse injection. The RTD curve is the concentration of tracer at the exit of the vessel as function of time.

A di¤erent approach to the analysis of residence times inside vessels is the numerical modeling by tanks

or volumes [3]. In these models the vessel is divided into dimerent regions (the tanks or volumes) where the tow is supposed to behave in a very simple way. For each volume, the concentration evolves according to a speci...c dimerential equation. The models presented in this paper are based on this method.

The numerical modeling of the ‡ow inside vessels by tanks or volumes is widely used in literature, as described in an extensive review published by Mazumdar and Guthrie [1]. Many of these works present models obtained by combinations of mixing volumes, plug ‡ow volumes and dead volumes [3]. However, a good description of RTD curves in terms of these models (called mixed ‡ow models) is not always possible. To improve the accuracy of the models, di¤erent modi...cations were introduced. Martin [4], for instance, proposed a modi...cation of the tank in series model (where the system is divided in several identical mixing volumes) by considering a non-integer number of tanks. Sahai and Ahuja [5], on the other hand, introduced the use of dispersed plug ‡ow volumes instead of the standard plug ‡ow volumes in their study of tundish RTD curves.

The dispersed plug ‡ow volume is based on the dispersion model introduced by Levenspiel and Smith [6] in the chemical reactor analysis, and represents a deviation from the ideal plug ‡ow caused by a longitudinal mixing. In the dispersion model the evolution of tracer concentration in any vessel is modeled by the one dimensional transient convection-di¤usion equation. Dispersion models describe accurately the mixing process if the di¤usivity is small , but are de...cient when di¤usivity is large [3], [7].

In Section IV we introduce a new kind of volume named convection-di¤usion volume. This volume is also based on dispersion models and is able to describe RTD curves in vessels with any amount of di¤usion. We comment the physical interpretation of this new convection-di¤usion volume and explain its di¤erence with the dispersed plug ‡ow volume. In Section III we propose a simple model consisting of a single convection-di¤usion volume and a dead volume; experimental RTD curves found in literature are analyzed in terms of this model. In order to represent two peaked RTD curves, another model is proposed in Section IV, which consists of two convection di¤usion volumes and a dead volume. This model is also used to analyze experimental data, specially two peaked RTD curves. In Section V we present a three dimensional numerical analysis of a four line tundish and the interpretation of its RTD curves in terms of the model described in Section IV. The last section is devoted to conclusions.

3

II Convection-Di¤usion volumes

A Basic equations

Let's consider a system with a volume V of ‡uid. The ‡uid enters and exits the system at a ‡ow rate Q. At the entrance of this system a tracer is being injected and we want to describe the concentration of tracer at the exit. A convection-di¤usion one dimensional equation model is used to represent the evolution of concentration of tracer inside the volume,

$$\frac{@C(x;\mu)}{@\mu} + \frac{@C(x;\mu)}{@x} = \frac{1}{Pe} \frac{@^{2}C(x;\mu)}{@x^{2}}:$$
(1)

where $C(x;\mu)$ is the dimensionless tracer concentration and x and μ are the dimensionless time and position expressed in terms of the length of the domain, L; and the theoretical residence time $\frac{V}{Q} = \frac{L}{v}$ (v is the velocity inside the domain, assumed constant). Pe is the turbulent Péclet number, $Pe = \frac{v}{D}$, where D is the turbulent di¤usivity.

We want to solve this equation for all 0 < x $\,$ 1 and μ > 0 according to the following initial and boundary conditions,

$$C(x; 0) = 0$$
 (2)
 $C(0; \mu) = C_0(\mu)$

where $C_0(\mu)$ is any given function of time.

$$C(\mathbf{x};\boldsymbol{\mu}) = \int_{0}^{Z_{\mu}} K_{Pe}(\mathbf{x};\boldsymbol{\mu}_{i};\boldsymbol{\lambda})C_{0}(\boldsymbol{\lambda})d\boldsymbol{\lambda}$$

where the kernel $K_{Pe}(x; \mu)$ is de...ned by

$$K_{Pe}(x;\mu) = x^{r} \frac{Pe}{4 \frac{1}{4} \mu^{3}} exp^{\mu}_{i} \frac{Pe(x_{i} \mu)^{2}}{4\mu}^{\P}$$

The kernel satis...es the dimerential equation, the initial condition and the integral property ${}^{R}_{0}$ $K_{Pe}(x;\mu) d\mu =$ 1 for all x > 0. Since the kernel vanishes at x = 0 for all μ > 0; the boundary condition for the kernel may be written as $K_{Pe}(0;\mu) = \pm(\mu)$, where $\pm(\mu)$ is Dirac's delta function. From these properties of the kernel it is possible to show that C (x; μ) satis...es Eq. (1) with conditions (2). We are interested in the concentration of tracer at the outlet of volume x = 1:

$$C(1;\mu) = \int_{0}^{Z_{\mu}} K_{Pe}(1;\mu_{i},j)C_{0}(j)dj$$
(3)

with $K_{Pe}(1;\mu)$ given by

$$K_{Pe}(1;\mu) = \int \frac{Pe}{4^{4}\mu^{3}} \exp \left[i \frac{Pe(1;\mu)^{2}}{4\mu}\right]^{q}$$
(4)

Now, we introduce the convection-di¤usion volume de…ned by its volume V and its Péclet number Pe: In this volume, if the concentration at the entrance $C_0(\mu)$ and the ‡ow rate Q are given, the concentration at the exit is calculated from Equation (3):

B Physical interpretation

From the properties described in the preceding section we can observe that, if $C(0;\mu) = \pm(\mu)$; then $C(1;\mu) = K_{Pe}(1;\mu)$. Consequently, the kernel $K_{Pe}(1;\mu)$ may be regarded as the tracer concentration leaving the system, when a pulse of concentration is injected at the system entrance at $\mu = 0$.

The convolution integral in Eq. (3) indicates that the outcoming concentration at time μ is in‡uenced by the whole history of the concentration at the entrance previous to time μ . Also, since the kernel at time μ is the response of the system to a pulse of concentration at the entrance at time $\mu = 0$, C(1; μ) may be considered as the response of the system to a series of pulses of amplitude C(0; λ)d λ injected at the entrance at time λ .

The set of equations described in the previous section were deduced under the assumption of open system. That is, the di¤usivity is considered continuous across the input - output boundaries of the system [7].

The Péclet number indicates how di¤usive the ‡ow in the system is.

- ² The limit Pe ! 1 corresponds to purely convective ‡ow with no di¤usion. In this limit $K_{Pe}(1;\mu)$! $\pm(1_i \ \mu)$ and $C(1;\mu)$! $C(0;1_i \ \mu)$. This is the expected solution for the concentration of tracer in a system with no di¤usion, that is, a plug ‡ow system.
- ² On the other hand, when Pe ! 0; di¤usion is very large and the concentration at the entrance propagates instantaneously along the volume. The function $K_{Pe}(1;\mu)$ presents a sharp peak near

 $\mu = 0$ vanishing anywhere else and $C(1; \mu)$! $C(0; \mu)$: This result contrasts with the large di¤usivity limit for closed systems $C(1; \mu)$! $R_0^{\mu} e^{i(\mu_i \cdot z)} C_0(z) dz$ [7].

Let's analyze the behavior of $C(1;\mu)$ in a convection-di¤usion volume when a pulse is injected at the entrance. In this case $C(1;\mu) = K_{Pe}(1;\mu)$ is the RTD curve of a system represented by a single convectiondi¤usion volume. Since C(1;0) = 0 (initial condition, Eq. (2)) and $C(1;\mu) ! 0$ as $\mu ! 1$ (from Eq. (4)), the curve must reach a maximum value C_p at a certain time μ_p : The general appearance of such a curve has already been shown in Figure 1. The values of μ_p and C_p are given by

$$\mu_{p} = \frac{i \ 3 + \frac{P_{0}}{9 + Pe^{2}}}{Pe}$$
(5)

and

$$C_{p} = C(1; \mu_{p}) = \frac{S - \tilde{A}}{4 \frac{\mu_{p}}{4 \mu_{p}}} \exp \left[\frac{\tilde{A}}{1 - \frac{\mu_{p}}{4 \mu_{p}}} \right]^{2} + \frac{P e (1 - \mu_{p})^{2}}{4 \mu_{p}} + \frac{1}{2} \exp \left[\frac{1}{4 \mu_{p}} + \frac{\mu_{p}}{4 \mu_{p}} \right]^{2} + \frac{1}{2} \exp \left[\frac{1}{4 \mu_{p}} + \frac{\mu_{p}}{4 \mu_{p}} + \frac{1}{2} \exp \left[\frac{1}{4 \mu_{p}} + \frac{\mu_{p}}{4 \mu_{p}} + \frac{1}{2} \exp \left[\frac{1}{4 \mu_{p}} + \frac{\mu_{p}}{4 \mu_{p}} + \frac{1}{2} \exp \left[\frac{1}{4 \mu_{p}} + \frac{\mu_{p}}{4 \mu_{p}} + \frac{1}{2} \exp \left[\frac{1}{4 \mu_{p}} + \frac{1}{4 \mu$$

The ...rst expression shows that $\mu_p ! 0$ when Pe ! 0 and $\mu_p ! 1$ when Pe ! 1. That is, in the limit of perfectly mixed ‡ow (Pe ! 0) the peak is at $\mu = 0$; since the concentration behaves as $\pm(\mu)$: For larger values of the Péclet number, μ_p increases. When the ‡ow is dominated by convection μ_p approaches the unity and in the limit of pure plug ‡ow $\mu_p = 1$; in agreement with the fact that, in this limit, the concentration tends to $\pm(1 + \mu)$: In consecuence the Péclet number can be estimated from the position of the RTD curve peak,

$$Pe = \frac{6 \,\mu_{\rm p}}{1_{\rm i} \,\,\mu_{\rm p}^2}:$$
(6)

C Comments on boundary condition

It is important to note that the dispersion model of Levenspiel and Smith makes use of a rather di¤erent function to describe the response of the system to a pulse injected at the entrance [6],

The kernel $\aleph_{Pe}(x;\mu)$ was obtained from a di¤erent solution of Eq. (1) (see reference [6]). At the entrance, this kernel does not represent a pulse, since it does not vanish for $\mu > 0$,

$$\aleph_{Pe}(0;\mu) = \frac{r}{\frac{Pe}{4 \sqrt{4}\mu}} \exp \frac{\mu}{i} \frac{Pe\mu}{4}$$

In Figure 2, the function $\aleph_{Pe}(0;\mu)$ is plotted as function of μ for dimerent values of the parameter Pe: For large values of the Péclet number (i.e. if dimusion is low) the concentration decreases rapidly away from $\mu = 0$ and in the limit Pe ! 1, $\aleph_{Pe}(0;\mu)$ tends to form of a pulse. However, for general values of Pe, $\aleph(0;\mu)$ presents long tails. This means that the tracer is injected at the entrance of the system during a certain period of time instead of being injected instantaneously at $\mu = 0$: The function $\aleph_{Pe}(x;\mu)$ can be regarded as the response of the system to a pulse at the entrance, but only in the limit of plug ‡ow. It is easy to see that in this limit,



Fig. 2: Concentration at the origin as function of time, for the solution of Eq. (1) described in reference [6]

It is also interesting to compare the average residence times, $\mu_{av} = {R_1 \atop 0} \mu K_{Pe}(1;\mu)d\mu$ and $\dot{\mu}_{av} = {R_1 \atop 0} \mu K_{Pe}(1;\mu)d\mu$: It can be seen that $\dot{\mu}_{av} = 1 + {2 \over Pe}$ (see reference [6]) only remains close to the unity in the limit of plug ‡ow and diverges on the limit of high di¤usion. On the other hand, $\mu_{av} = 1$ for any value of Pe:

III A simple vessel model

In this Section we will describe the whole vessel with a very simple model composed by a convection di¤usion volume (V_a : active volume) and a dead volume ($V_d = V_i V_a$), to take into account dead or slowly moving tow regions. It is assumed that in the active zone the tow behaves as one dimensional with a characteristic time $\frac{V_a}{\Omega}$. When the concentration at the entrance of the model corresponds to a pulse, the concentration at the exit of the model can be obtained from Eq. (3)

$$C(1;\mu) = \frac{1}{v_a} K_{Pe} {}^{\mu} 1; \frac{\mu}{v_a} {}^{\P} = {}^{\Gamma} \frac{\overline{v_a Pe}}{\frac{4}{4} \mu^3} \exp {}^{i} i \frac{Pe(v_a i \mu)^2}{4 v_a \mu} {}^{!}$$
(7)

which is the mathematical expression for the RTD curve. This curve reaches its maximum when

$$\mu_{p} = v_{a} \frac{i \ 3 + \frac{P_{q}}{9 + Pe^{2}}}{Pe}:$$
(8)

The model has two dimensionless parameters, the Péclet Number Pe and the fraction of the active volume $v_a = V_a = V$. It is useful to relate these parameters to the values of μ_p ; C_p and μ_{av} (where $\mu_{av} = \frac{R_1}{0} \mu C(1; \mu) d\mu$ is the average residence time). The following expressions were obtained,

$$v_a = \mu_{av} \tag{9}$$

$$V_{d} = 1_{i} \ \mu_{av}$$

$$Pe = \frac{6}{\mu_{av}^{2} \mu_{av}^{2}} \frac{\mu_{av}}{\mu_{av}^{2}}$$
(10)

Then, the parameters of the simple vessel model v_a and Pe can be estimated from the values of μ_{av} and μ_p of an experimental RTD curve.

However, the numerical calculation of μ_{av} from experimental curves can be di¢cult, specially for RTD curves with very long tails. In order to ...nd another way to estimate the parameters of the model, the product $C_p \mu_p$ is going to be considered. This product does not depend on v_a and is only function of Pe;

$$C_{p}\mu_{p} = a(Pe) = \frac{Pe}{4\frac{1}{4}i_{j}^{2}3 + \frac{P}{9 + Pe^{2}}} exp_{j} \frac{i_{Pe+3}}{4i_{j}^{2}3 + \frac{P}{9 + Pe^{2}}} exp_{j} \frac{i_{Pe+3}}{4i_{j}^{2}3 + \frac{P}{9 + Pe^{2}}} (11)$$

In a RTD diagram, a(Pe) represents the rectangular area subtended by the origin and the peak of the curve (see Figure 3) and is a monotonous increasing function of the Pe (see Figure 4). We found that

a(Pe) ! a_0 ' 0:154 when Pe ! 0, and that a(Pe) ! $\begin{array}{c} Q_{\frac{Pe}{4}i} i \\ \frac{Pe}{4}i \end{array}$ i $1_i \frac{3}{4Pe} c^{\text{t}}$ when Pe ! 1. This asymptotic expression can be inverted to obtain a good estimation of Pe when the ‡ow has small degree of di¤usion,

$$A = S - \frac{1}{4} \frac{1}{4} + 2\frac{1}{4} (C_{p}\mu_{p})^{2} + \frac{1}{1} + \frac{3}{4\frac{1}{4} (C_{p}\mu_{p})^{2}}$$
(12)

For Pe > 5 (which corresponds to a > 0:55), the Péclet number can be approximated by this expression with an error smaller than 5 %:



Fig. 3: Relationship between the location of the peak

of the RTD curve and the function a(Pe).



Fig. 4: Function a(Pe) which relates de Peclet number to the location of the peak of the RTD curve..

Case	1	2	
Authors	Barrón-Meza et al	Zong et al.	
Reference	[8]	[9]	
V [I]	13.7	30.0	
Q [l=s]	0.2066	0.0666	
type of vessel	one strand tundish	continuous rening vesse	
Number of Figure	5,6 and 7	8, 9 and 10	

Table I: Cases considered for the validation of the

simple vessel model.

A Validation of the simple vessel model

The validation of the simple vessel model proposed in this section was carried out by matching two experimental RTD curves found in literature and described in Table I.

The matching of experimental data was carried out using three dimerent procedures to estimate the parameters Pe and v_a ,

Procedure 1: Minimization of the square of the distance between the numerical results of Eq. (7) and the experimental data of the RTD curves, using the Levenberg-Marquardt algorithm. Figures 5 and 8 show the results for this procedure for the two cases described in Table I.

Procedure 2: Numerical estimation of the average residence time using the experimental data and evaluation of Pe and v_a using Eq. (10) and Eq. (9). The resulting RTD curves are presented in Figures 6 and 9 for both cases.

Procedure 3: Evaluation of the product $\mu_p C_p$ from the RTD curve and calculation of Pe from Figure 4 or from Eq. (11) (in this case a nonlinear equation must be solved using, for example, a Newton Raphson technique) or using the asymptotic expression Eq. (12). Finally v_a is obtained from Eq. (8). Results are shown in Figures 7 and 10.

The values Pe and v_a obtained with the dimerent procedures for both cases are shown in Table II. The procedure 1 provides the best ...tting but involves the solution of a nonlinear minimization problem.

Procedure	Parameter	Case1	Case2
1	Pe	5.26	3.64
1	va	1.0	0.84
2	Pe	4.11	3.77
2	Va	0.97	0.76
3	Pe	4.198	3.02
3	va	0.96	0.88

Table II: Numerical values of the parameters Pe and

Procedures 2 and 3 give a reasonable estimation of the parameters with very little information from the experimental data. The accuracy of these two procedures depend strongly on the reliability of the evaluation of μ_p and μ_{av} or C_p ; from the experimental RTD curve.



Fig. 5: Comparison of experimental results [8] and the simple vessel model with a least square matching (procedure 1).

Va



Fig. 6: Comparison of experimental results [8] and the simple vessel model using Eq. (10) and Eq. (9) (procedure 2).



Fig. 7: Comparison of experimental results [8] and the simple vessel model using Eq. (11) and Eq. (8) (procedure 3)



Fig. 8: Comparison of experimental results [9] and the simple vessel model with a least square matching (procedure 1).



Fig. 9: Comparison of experimental results [9] and the simple vessel model using Eq. (10) and Eq. (9) (procedure 2).



Fig. 10: Comparison of experimental results [9] and the simple vessel model using Eq. (11) and Eq. (8) (procedure 3).

IV A multivolume vessel model

The model described above succeeded in representing a variety of experimental RTD curves. However it fails to describe correctly RTD curves with two peaks. These curves arise when short circuits are present in the system [10]. Consequently a model consisting of two convection-di¤usion volumes connected in parallel and a dead volume is proposed (Figure 11).

For a steady state problem where both the \ddagger ow rate at the entrance of the vessel Q_{in} , and the \ddagger ow rate at the exit of the vessel, Q_{out} , are constant in time, the following relations hold

$$Q_{in} = Q_{out} = Q^1 + Q^2 = Q$$
; $Q_d = 0$

The entrance tracer pulse is modeled by a Dirac's delta function

$$C_{in}(\mu) = C_{in}^{1}(\mu) = C_{in}^{2}(\mu) = \pm(\mu)$$
(13)

To calculate the dimensionless concentration at the exit of each of the convection-di¤usion volumes, Equation (3) must be applied, with Eq. (13) as boundary condition. For volume i (i = 1; 2) the following



Fig. 11: Scheme of the multivolume tundish model.

expression is obtained

$$C_{out}^{i}(\mu) = \frac{q^{i}}{f_{V}^{i}} K_{Pe^{i}} \overset{\mu}{\xrightarrow{}} 1; \mu \frac{q^{i}}{f_{V}^{i}} \P$$

where the relative \ddagger ow rate $q^i = Q^i = Q$ and the volume fraction $f_V^i = V^i = V_T$ were introduced.

Finally the concentration exiting the system is obtained by tracer conservation which leads to the following expression

$$C_{out}(\mu) = \frac{i_{q1}^{\ell_2}}{f_V^1} K_{Pe^1} \overset{\mu}{1}; \mu \frac{q^1}{f_V^1} \overset{\P}{+} \frac{i_{q2}^{\ell_2}}{f_V^2} K_{Pe^2} \overset{\mu}{1}; \mu \frac{q^2}{f_V^2} \overset{\P}{+}:$$
(14)

This expression contains ...ve dimensionless parameters, f_V^1 ; f_V^2 ; q^1 ; Pe^1 and Pe^2 (the parameter q^2 is given by $q^2 = 1_i q^1$). All the parameters must be positive and the volume fractions must satisfy the inequality $f_V^1 + f_V^2 = 1$: Note that the dead volume in‡uences the result indirectly by reducing the convection-di¤usion region (otherwise $f_V^1 + f_V^2 = 1$).

Any experimental RTD curve is expected to be well represented by Equation (14) if suitable values for the parameters are chosen. A numerical code (RESIDENCE [11]) was developed to ...nd the set of parameters which minimizes (in a L^2 sense) the distance between a given experimental curve and $C_{out}(\mu)$: This program

Case	Authors	V [I]	Q [I=S]	Vessel type	Figure
1	Barrón Meza et.al [8]	13:7	0:2066	one strand tundish	12
2	Zong et al [9]	30:0	0:0666	continuous rening vessel	13
3	Chakraborty et al[13]	186:3	0:5046	one strand tundish	14
4	Singh et al[10]	86:2	0:155	one strand tundish	15
5	Zong et al [9]	30:0	0:0666	continuous rening vessel	16

Table III: Di¤erent RTD curves considered for the

validation of the model

Cases	f_V^1	f_V^2	q1	Pe ₁	Pe ₂
1	0:00	1:00	0:00	1:00	5:26
2	0:23	0:54	0:23	12:12	4:00
3	0:29	0:71	0:42	3:03	5:63
4	0:87	0:025	0:87	3:59	6:64
5	0:0083	0:76	0:045	223:7	4:34

Table IV: Optimal values of the parameters.

was codi...ed in Fortran and makes use of the IMSL subroutine DBCLSF, which solves nonlinear least squares problems using a modi...ed Levenberg -Marquardt algorithm [12].

A Validation of a multivolume vessel model

In order to validate the multivolume model, several experimental measurements found in literature are going to be considered. In Table III we present the di¤erent cases to be analyzed.

In Table IV we show the optimal values obtained by our program RESIDENCE [11] and in the Figures 12 to 16 we compare numerical results and experimental measurements.

Case 1 (Figure 12) has already been considered in the previous section and was matched with the simple model. From Table IV we see that the addition of a convection di¤usion volume does not a¤ect the results.







Fig. 13: Comparison of experimental results [9] and the multivolume vessel model.

Only one convection-di¤usion volume was really needed, since both f_V^1 and q^1 vanish.

Case 2 (Figure 13) has also been addressed in the previous section. However in this case an improvement in the accuracy of the approximation was achieved by the multivolume model.

The third example, taken from Chakraborty and Sahai [13], is plotted in Figure 14. For this RTD curve, a traditional analysis becomes troublesome since numerical integration of the experimental data renders $\mu_{av} > 1$: However, the numerical results given by the multivolume vessel model show a reasonable agreement with the experimental points.



Fig. 14: Comparison of experimental results [13] and the multivolume vessel model.

Up to now we have presented examples of RTD curves with a single peak. In case 4 (Figure 15) we consider a two peaked RTD curve measured by Singh and Koria [10]. In this case each peak could be associated to a volume, the sharpest peak corresponding to the smallest volume: Obviously, this kind of curve could not be reasonably approximated by a single convection-di¤usion volume.

Another example of two peaked RTD curve is shown in Figure 16. Experimental points were also taken from the work by Zong et al. [9] (with the water model described in the second example). Like the previous example, the extremely sharp peak due to a short-circuit is modeled by a very small convection di¤usion volume, V_1 ; with a high Péclet number.



Fig. 15: Comparison of experimental results [10] and the multivolume vessel model.



Fig. 16: Comparison of experimental results [9] and the multivolume vessel model.

V Analysis of a multiple line tundish

We present an example corresponding to a four line tundish with the volume of 3:44 m³ and a ‡ow rate of 49:94 I=min in each line. In a multiple line tundish, it is of interest to model the RTD curve resulting from the addition of the RTD curves of each line [1].

In this example the RTD curves were obtained by the following procedure:

- ² The liquid steel ‡ow inside the tundish was calculated with a 3D numerical model using (k-L)-predictor /(")-corrector turbulent model (where k is the turbulent kinetic energy, " is the dissipation rate of k, and L is the mixing length). This numerical model was developed and tested in our previous publication [14]-[19]
- ² Once the velocity ...eld and turbulence variables were obtained, the tracer transport equation in a turbulent stream was calculated by solving a transient 3D turbulent convection-di¤usion equation [20].

In the Figure 17 the internal and external lines of a symmetric four line tundish are shown, together with the global RTD curve. The approximation of the global RTD curve, also shown in Figure 17, is obtained using the multiple volume model described in section IV.



Fig. 17: Numerical results from a three dimensional model of a four line tundish compared to results from the present model

The values of the parameter obtained for this case are: $f_V^1 = 0.56$; $f_V^2 = 0.36$; $q^1 = 0.54$; $Pe_1 = 9.01$; $Pe_2 = 1.96$

VI Conclusions

Two numerical models for the simulation of RTD curves in di¤erent vessels are presented. The comparison of measured RTD curves with numerical results from the proposed models shows that these models can successfully represent the general behavior of the ‡uid inside a variety of systems. The RTD curves used for validation of the model include experimental data found in literature and numerical data obtained from a full three dimensional computation of the turbulent ‡ow in a tundish.

The …rst of the models proved to be e⊄cient to describe most of the one peaked RTD curves, in spite of its simplicity. The second one, slightly more complex, represented successfully all the di¤erent RTD curves under consideration, including those with two peaks.

The key feature of these models is the use of a new type of volume -the convection-di¤usion volumeintroduced in this work. The characteristics of this volume were deduced from the convection-di¤usion one dimensional equation with a pulse boundary condition in the origin. For this reason, the use of convection-di¤usion volume is not restricted to systems that exhibit small degree of mixing. This allows the representation of the di¤erent vessels with very simple models.

In order to ...nd the parameters of the model for a given experimental RTD curve, a numerical algorithm was developed. We also found some simple mathematical relations that allow the estimation of the parameters of the model from the characteristic parameters of the RTD curve.

List of Symbols

a(Pe)	Area subtended by the origin and the peak of the curve in a RTD plot.[dimensionless]
С	Dimensionless concentration
C ₀	Dimensionless concentration at the vessel entrance.
Cp	Dimensionless concentration of the peak of the RTD curve
D	Mean turbulent di¤usivity [mm ² =sec]
f_V^i	Volume fraction [dimensionless]
K _{Pe}	Kernel associated to the convection-di¤usion volume [dimensionless]
k _{Pe}	Kernel developed by Levenspiel and Smith [6] [dimensionless]
L	Length of the 1D domain [mm]
Pe	Péclet number [dimensionless]
q ⁱ	Relative ‡ow rate [dimensionless].
Q	Flow rate in the vessel [mm ³ =sec]
V	Mean velocity inside the 1D domain [mm/sec]
Va	Active volume fraction [dimensionless].
V _d	Dead volume fraction [dimensionless].
V	Volume of the vessel [mm ³]
х	Dimensionless coordinate along the ‡ow direction.
μ	Dimensionless time
μ_{p}	Dimensionless time for the peak of the RTD curve
μ_{av}	Average residence time [dimensionless].
ż	Theoretical residence time [sec]

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